



Investmech: Static failure criteria

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Contents



- Properties of materials
- Calculation of Principal Stresses
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Remember to always include the design class of the structure in failure theories. For example, multiple load paths classify a structure as **fail-safe**, and other structures are designed for **safe-life**

In **safe-life** applications, **damage tolerant** design is essential

Material properties



- Brittleness: Breaks or powders easily
- Malleability: May be pounded into thin sheets
- Ductility: Can be plastically deformed. Material must be tough & malleable!
- Sectility: May be cut smooth with a knife
- Elasticity: Spring back to original position when stress is released
- Plasticity: Can be deformed plastically
- Flexibility: Ability to deform elastically and return to original shape when stress is released
- Creep
- Resilience¹
 - Ability to absorb energy when it is deformed elastically
 - Modulus of Resilience: $U_r = \frac{\sigma_y \epsilon_y}{2} = \frac{\sigma_y^2}{2E}$
 - References: [https://en.wikipedia.org/wiki/Resilience_\(materials_science\)](https://en.wikipedia.org/wiki/Resilience_(materials_science)); <https://www.nuclear-power.net/nuclear-engineering/materials-science/material-properties/resilience/>; <https://www.education.sau.edu/materials/properties/>
- Toughness
 - Energy that can be absorbed and still keep going
- Tenacity:
 - Reaction of materials to stress (crushing, bending, breaking, tearing). How material behaves.
 - <https://www.nuclear-power.net/nuclear-engineering/materials-science/material-properties/tenacity/>

1.
[https://en.wikipedia.org/wiki/Resilience_\(materials_science\)](https://en.wikipedia.org/wiki/Resilience_(materials_science)); <https://www.nuclear-power.net/nuclear-engineering/materials-science/material-properties/resilience/>; <https://www.education.sau.edu/materials/properties/>

Calculation of principal stresses



- To calculate the stress in any direction use:

$$\sigma_n = l^2\sigma_x + m^2\sigma_y + n^2\sigma_z + 2(lm\tau_{xy} + nl\tau_{xz} + mn\tau_{yz})$$

- l , m and n are the direction cosines of the unit vector directing in the direction in which the stress is required
- The general form of stress transformation:

$$\sigma'_{ij} = \sum_{n=1}^3 \sum_{m=1}^3 l_{im} l_{jn} \sigma_{mn}$$

Where l_{im} is the direction cosine of angle between axes i and m

- $\tau_{ij} = \sigma_{ij} = \sigma_{ji}$

Stress tensor transformation



- Stress tensor transformation

$$\sigma_n = \begin{bmatrix} \ell_1 & m_1 & n_1 \\ \ell_2 & m_2 & n_2 \\ \ell_3 & m_3 & n_3 \end{bmatrix} \begin{bmatrix} \sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} \end{bmatrix} \begin{bmatrix} \ell_1 & \ell_2 & \ell_3 \\ m_1 & m_2 & m_3 \\ n_1 & n_2 & n_3 \end{bmatrix} = \mathbf{r}^T \boldsymbol{\sigma}_{old} \mathbf{r}$$

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Principal normal stresses



Where:

$$\begin{vmatrix} \sigma - \sigma_x & -\tau_{xy} & -\tau_{xz} \\ -\tau_{yx} & \sigma - \sigma_y & -\tau_{yz} \\ -\tau_{zx} & -\tau_{zy} & \sigma - \sigma_z \end{vmatrix} = 0$$

Therefore:

$$\sigma^3 - \sigma^2(\sigma_x + \sigma_y + \sigma_z) + \sigma(\sigma_x\sigma_y + \sigma_y\sigma_z + \sigma_x\sigma_z - \tau_{xy}^2 - \tau_{xz}^2 - \tau_{yz}^2) - (\sigma_x\sigma_y\sigma_z + 2\tau_{xy}\tau_{xz}\tau_{yz} - \sigma_x\tau_{yz}^2 - \sigma_y\tau_{xz}^2 - \sigma_z\tau_{xy}^2) = 0$$

To calculate in Matlab:

$E = \text{EIG}(X)$ is a vector containing the eigenvalues of a square matrix X. Note that X in this case is numerical stress values

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Principal stress example



- Multi-axial stresses:
- Principal stresses:

$$\sigma_x = 600 \text{ MPa}$$

$$\sigma_y = 0 \text{ MPa}$$

$$\sigma_z = 0 \text{ MPa}$$

$$\tau_{xy} = 400 \text{ MPa}$$

$$\tau_{xz} = 0 \text{ MPa}$$

$$\tau_{yz} = 0 \text{ MPa}$$

$$\gg X = [600 \ -400 \ 0; \ -400 \ 0 \ 0; \ 0 \ 0 \ 0];$$

$$\gg E = \text{eig}(X)$$

$$E =$$

$$800 = \sigma_1$$

$$-200 = \sigma_3$$

$$0 = \sigma_2$$

The principal stresses are ordered from large to small for σ_1 to σ_3

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Principal axes vectors and Eigenvectors



- The Matlab command is: `[V,D]=eig(X)`;
- D contains the eigenvalues and the **columns of V** represent the eigenvectors
- Example with values in previous example:

Example 1

```
>> [V,D]=eig(X)
```

```
V =
```

```
-0.4472    0 -0.8944
-0.8944    0  0.4472
    0  1.0000    0
```

```
D =
```

```
-200    0    0
    0    0    0
    0    0  800
```

Example 2

```
>> X=[600 0 0; 0 200 0; 0 0 100];
```

```
>> [V,D]=eig(X)
```

```
V =
```

```
0  0  1
0  1  0
1  0  0
```

```
D =
```

```
100  0  0
    0 200  0
    0  0 600
```

Static failure theories



- Maximum Principal (Normal) Stress (Lamé)
- Maximum Shear Stress (Tresca)
- Von Mises
- Octahedral stress
- Mohr's theory
- Buckling
- Maximum principal strain (St. Venant)
- Total strain energy (Beltrami-Haigh)
- Maximum distortion energy

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Maximum Principal Stress (Lamé)



- Calculate σ_1, σ_2 and σ_3

$$\sigma_N = \max(|\sigma_1|, |\sigma_2|, |\sigma_3|)$$
- Failure when:

$$\sigma_N = \sigma_u \text{ or } \sigma_o$$
- Safety factor against failure:

$$X = \frac{\sigma_u}{\sigma_N}$$
- Also used:
 - f_y - the material's yield strength
 - or f_{ut} - the material's tensile strength
- Note, some materials may have different tensile and compressive failure resistances
- SANS 10162-1 for structural steel use factored resistance: $0.9f_y$ for structural steel

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Maximum Shear Stress (Tresca)



- The maximum shear stress is calculated as follows:

$$\tau_{max} = \frac{\sigma_1 - \sigma_3}{2}$$

- Failure occurs when:

$$\begin{aligned} \tau_{max} &\geq \frac{\sigma_f}{2} \\ \therefore |\sigma_1 - \sigma_2| &\geq \sigma_f \\ |\sigma_1 - \sigma_3| &\geq \sigma_f \\ |\sigma_2 - \sigma_3| &\geq \sigma_f \end{aligned}$$

Dowling recommends: $\sigma_f = \sigma_o$

Equation indicates that under hydrostatic stress state, the maximum shear stress is zero! In agreement with test results under compression. Under tension, use maximum principal stress criterion

σ_f is the fracture stress. The yield strength, ultimate tensile strength, or any other allowable strength may be used.

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Von Mises Theory



- Equation:

$$\begin{aligned} \sigma_{vm} &= \frac{1}{\sqrt{2}} \sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_1 - \sigma_3)^2 + (\sigma_2 - \sigma_3)^2} \\ &= \frac{1}{\sqrt{2}} \sqrt{(\sigma_x - \sigma_y)^2 + (\sigma_y - \sigma_z)^2 + (\sigma_z - \sigma_x)^2 + 6(\tau_{xy}^2 + \tau_{yz}^2 + \tau_{zx}^2)} \end{aligned}$$

- Failure occur when:

$$(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_1 - \sigma_3)^2 \geq 2\sigma_f^2$$

- In most cases the failure stress is taken as the material yield strength

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Octahedral Shear Stress Theory = von Mises theory = distortion energy theory



- Equation:

$$\begin{aligned}\tau_{oct} &= \frac{1}{3} \sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_1 - \sigma_3)^2 + (\sigma_2 - \sigma_3)^2} \\ &= \frac{1}{3} \sqrt{(\sigma_x - \sigma_y)^2 + (\sigma_y - \sigma_z)^2 + (\sigma_z - \sigma_x)^2 + 6(\tau_{xy}^2 + \tau_{yz}^2 + \tau_{zx}^2)}\end{aligned}$$

- The octahedral shear stress at failure:

$$\tau_{oct} = S_{xy} = \frac{\sqrt{2}}{3} f_y$$

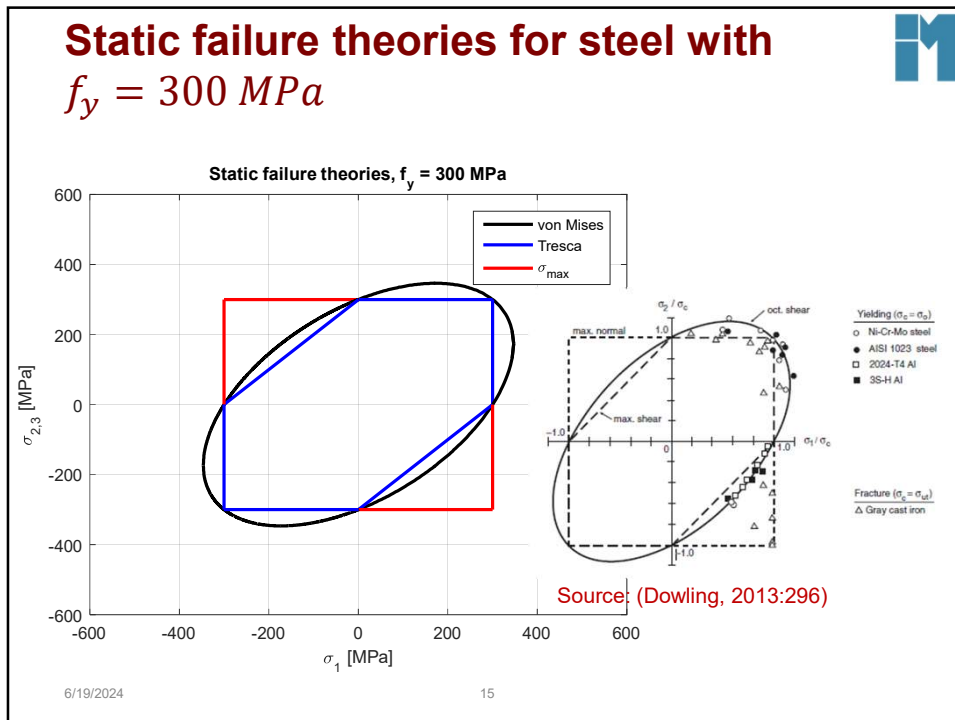
- In most cases the failure stress is taken as the material yield strength

Distortion-energy theory



- Is also called the:
 - Von Mises or von Mises-Hencky theory
 - Shear-energy theory
 - Octahedral-shear-stress theory

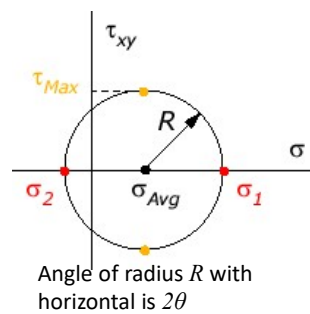
Static failure theories for steel with $f_y = 300 \text{ MPa}$



Mohr's failure theory

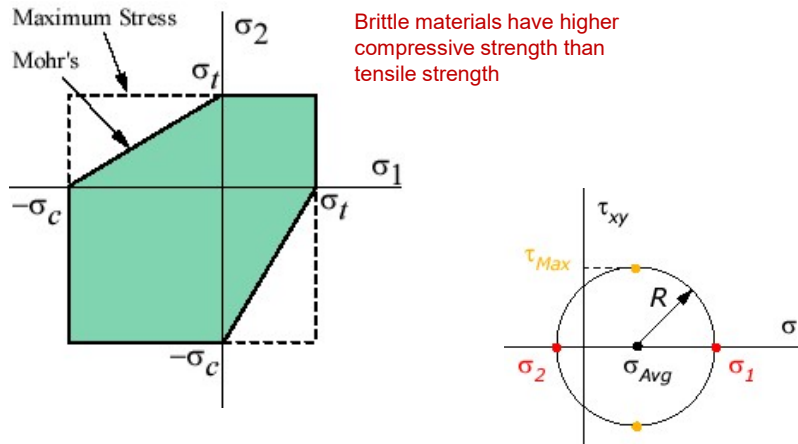


- Also known as
 - Coulomb-Mohr criterion
 - Internal friction theory
- Based on the Mohr's circle



Case	Principal stresses	Criterion requirements
1	Both in tension $\sigma_1 > 0,$ $\sigma_2 > 0$	$\sigma_1 < \sigma_t$ $\sigma_2 < \sigma_t$
2	Both in compression $\sigma_1 < 0,$ $\sigma_2 < 0$	$\sigma_1 > -\sigma_c$ $\sigma_2 > -\sigma_c$
3	σ_1 in tension, σ_2 in compression $\sigma_1 > 0,$ $\sigma_2 < 0$	$\frac{\sigma_1}{\sigma_t} + \frac{\sigma_2}{-\sigma_c} < 1$
4	σ_1 in compression, σ_2 in tension $\sigma_1 < 0,$ $\sigma_2 > 0$	$\frac{\sigma_1}{-\sigma_c} + \frac{\sigma_2}{\sigma_t} < 1$

Mohr's vs. Maximum Stress criteria



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Other failure theories



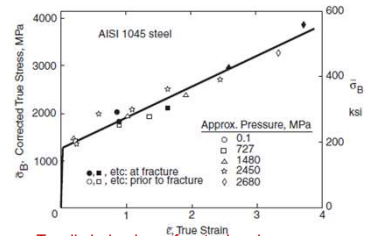
- Maximum normal strain theory (St. Venant's theory)
 - Use for:
 - Crash simulations
 - Furnace design due to refractory reheating
 - For welded detail on structural steel, Investmech uses maximum strain of 21%
- Total strain energy theory (Beltrami theory)

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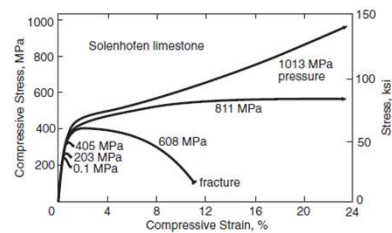
Brittle vs ductile behaviour



- Ductile
 - Static strength generally limited by yielding
 - Metals & Polymers
 - Mode of failure is dislocation motion
- Brittle
 - Generally limited by fracture
 - Gray cast iron & other cast metals
 - Stone, ceramics and glasses
 - Concrete
 - Do not exhibit well-defined yielding behaviour
 - Fail after small elongation $\leq 5\%$
 - May exhibit considerable elongation under hydrostatic compressive stress



Tensile behaviour of a steel under pressures



Stress-strain of limestone cylinders under axial compression subject to hydrostatic pressures

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Which one do I use?



Results showed:

- Ductile materials ($> 5\%$ elongation @ break)
 - Main yield mechanism is dislocation motion in ductile materials
 - Maximum shear stress
 - Von Mises
 - Maximum principal stress
- Brittle materials ($\leq 5\%$ elongation @ break)
 - Brittle material has $\sigma_{tension} \ll \sigma_{compression}$
 - Maximum principal stress (Lamé)
 - Mohr-Coulomb theory

Investmech:

- Applies maximum principal stress & von Mises theories for static design
- For fatigue, principal stresses are calculated – that is the basis for the S-N curves
- Crashworthiness, furnace design, etc (plastic deformation occurs)
 - Maximum engineering strain (e.g. 21% for welded structural steel)
 - True principal strain

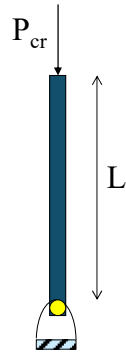
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Buckling



- Pinned-End column



$$P_{cr} = \frac{\pi^2 EI}{L^2}$$

Many textbooks has equations for different end supports on the critical load on columns.

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Non-stress-based criteria



- Success of parts not necessarily determined by strength
 - Stiffness, vibrational characteristics, fatigue resistance, creep resistance
- Example
 - Rigidity in automotive vehicles
 - Weight reduction in bicycles
 - Patio deck – stiffness to prevent excessive deformation

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Conclusion



- Always look at all failure criteria
 - The one that prevails first will be the mode in which failure will occur
- For furnaces: maximum strain of 20% for heat-up cycles
- Fatigue analysis concerns the calculation of “damage” to the structure and is the life until a detectable crack initiates
- Fracture Mechanics determines failure during the crack growth phase